

# Software Measurement

SMEF 2004

## A Proposed Measurement Role in the Rational Unified Process and its Implementation with ISO 19761: COSMIC-FFP

Saadi Azzouz, Alain Abran  
École de Technologie Supérieure – ETS  
Montréal, Québec, Canada.

[azzouz.saadi@courrier.uqam.ca](mailto:azzouz.saadi@courrier.uqam.ca) [aabran@ele.etsmtl.ca](mailto:aabran@ele.etsmtl.ca)

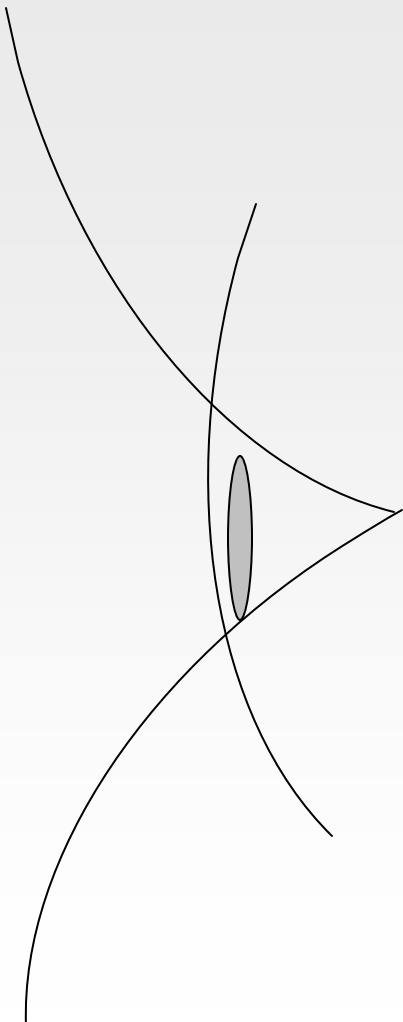


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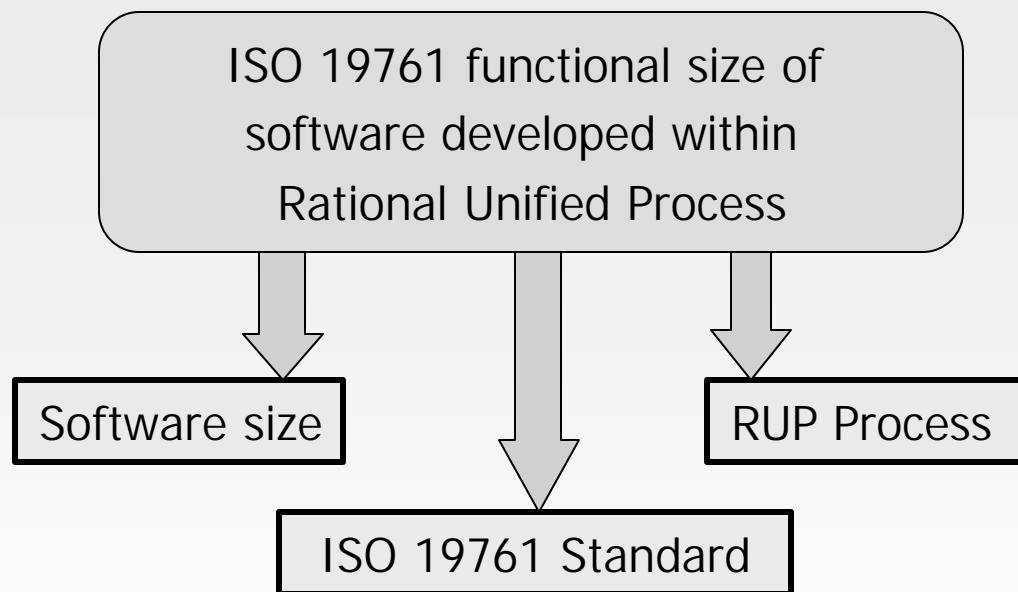
# Summary

- Objective
- Software size
- Standard ISO 19761
- RUP new measurement activity
- Tool measurement basis
- Solution
- Results
- Conclusion



# Functional Size Measurement

## Objective



*Predict – Measure software size at the first steps of development process*



# ISO 19761 Standard

## **COSMIC-FFP**

**Common Software Measurement International  
Consortium - Full Function Point**

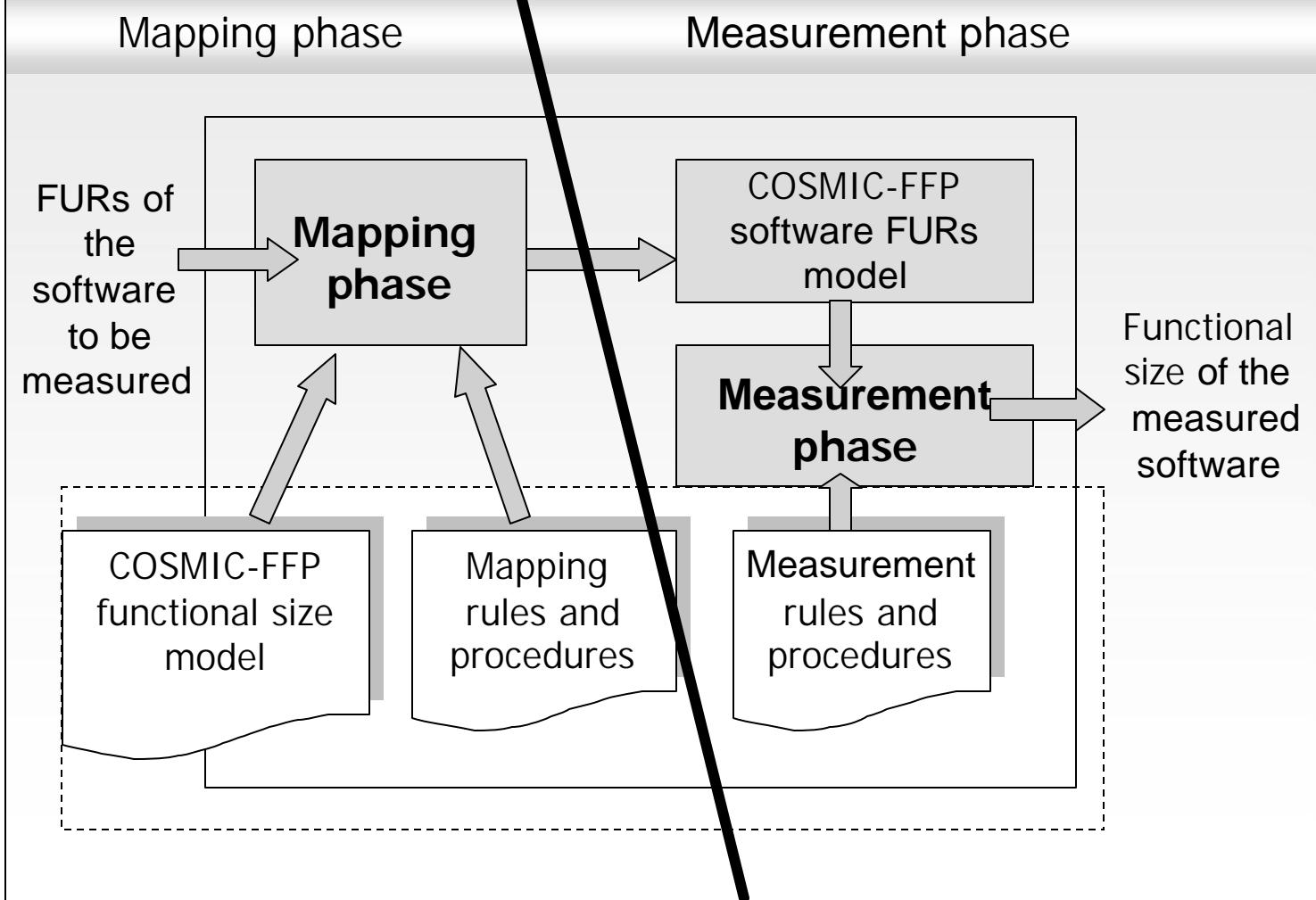


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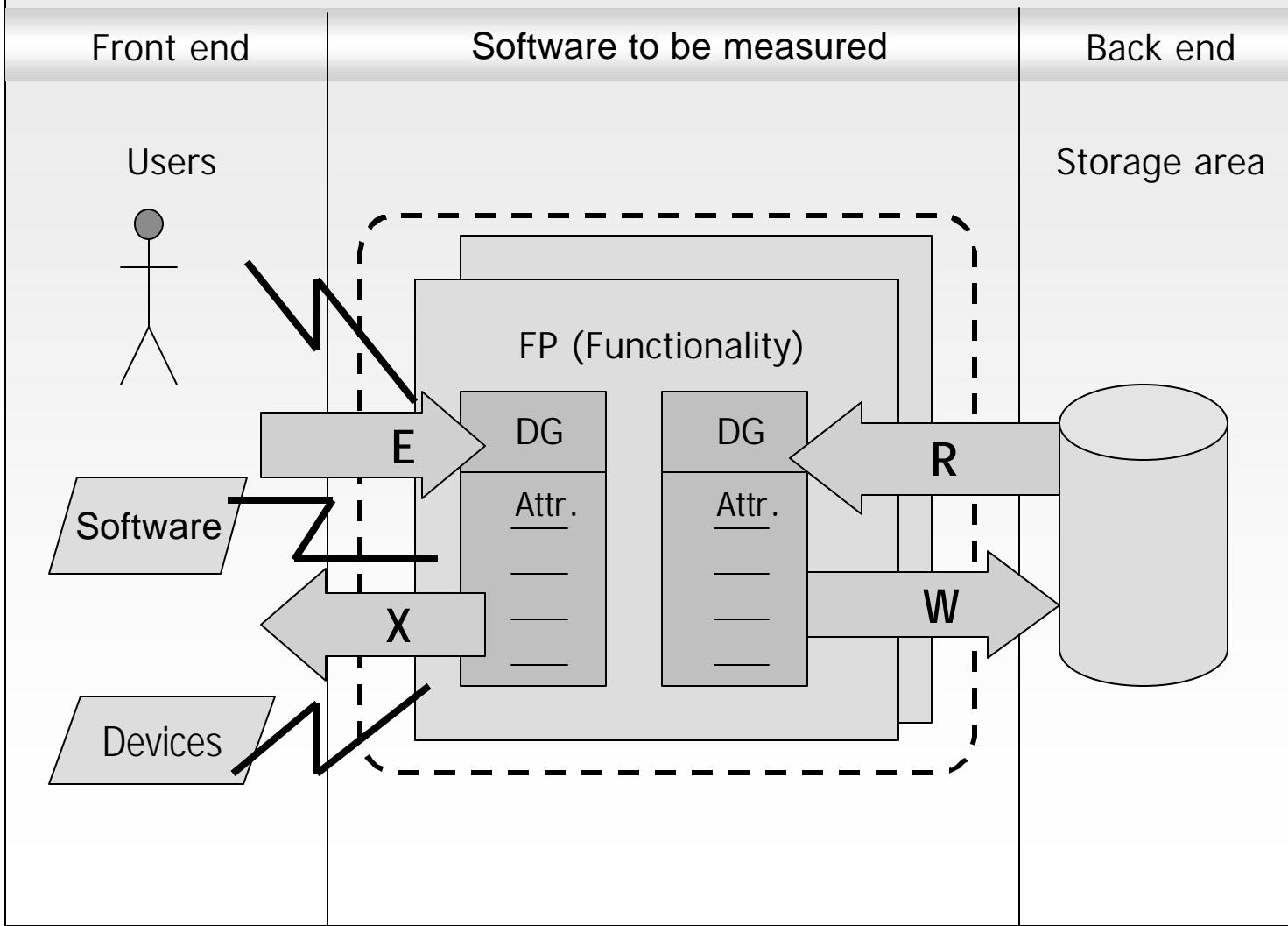
# ISO 19761 Standard

## COSMIC-FFP phases



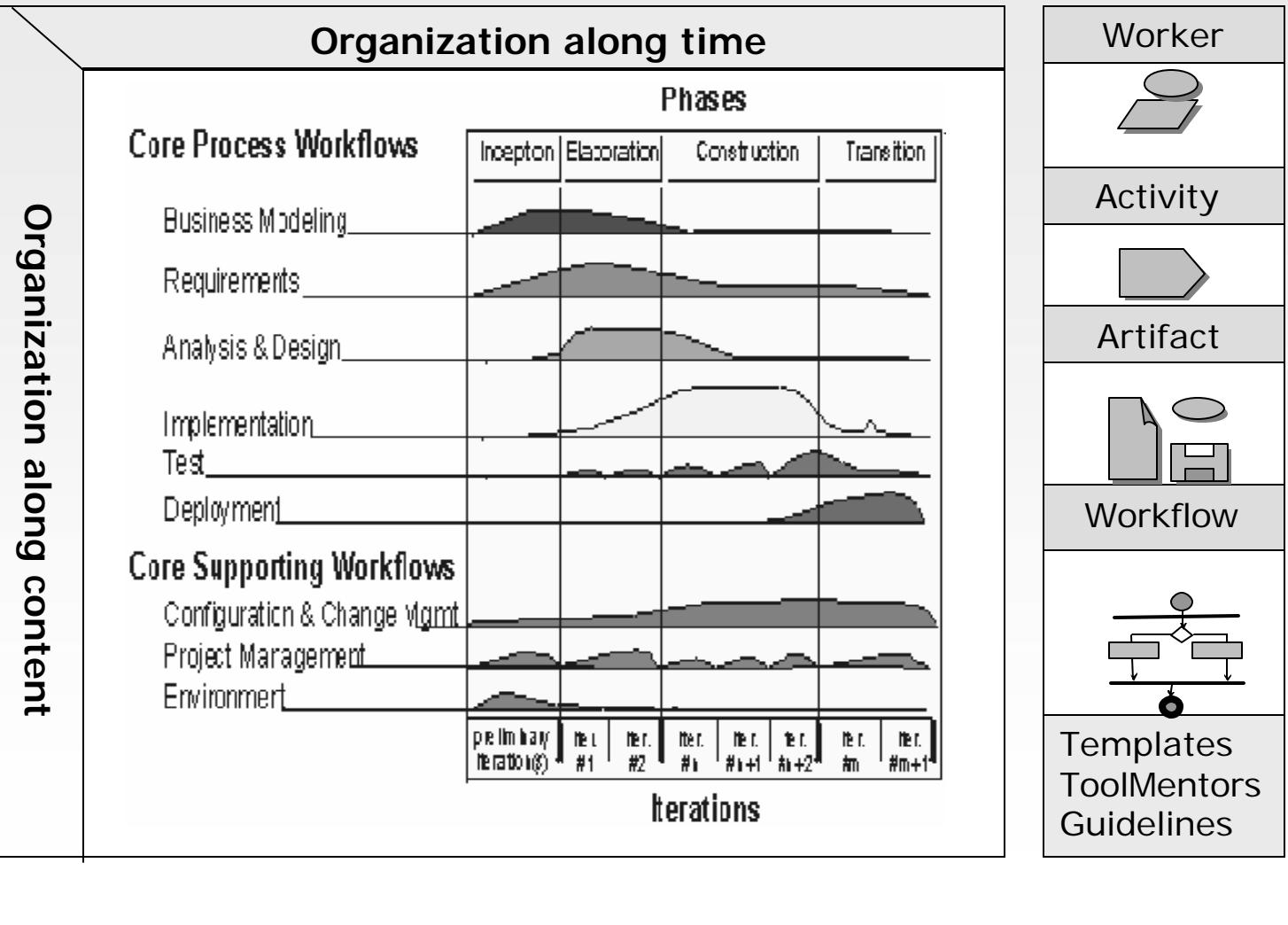
# ISO 19761 Standard

## Generic data flow

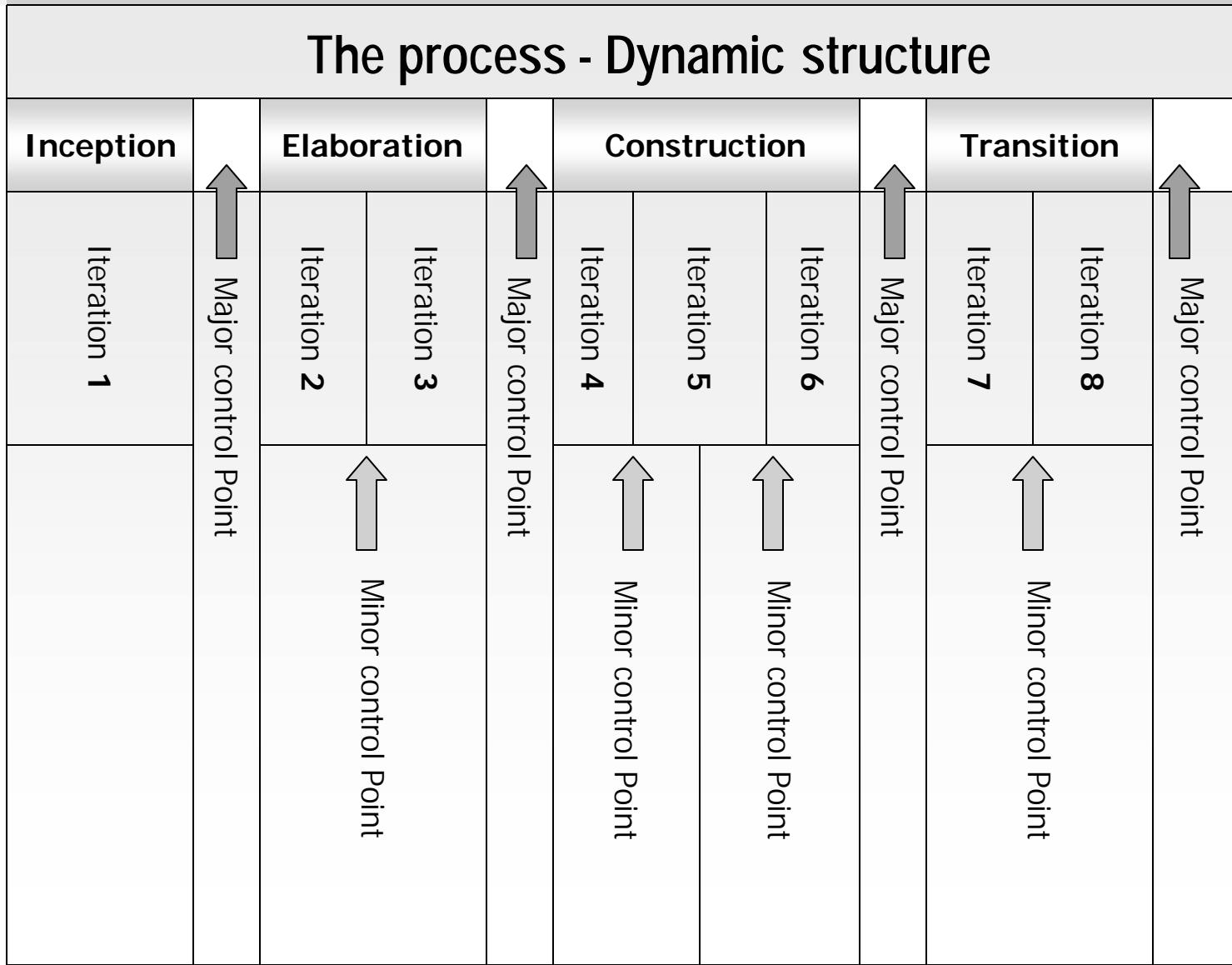


# RUP and measurement activity

## The process - Static structure

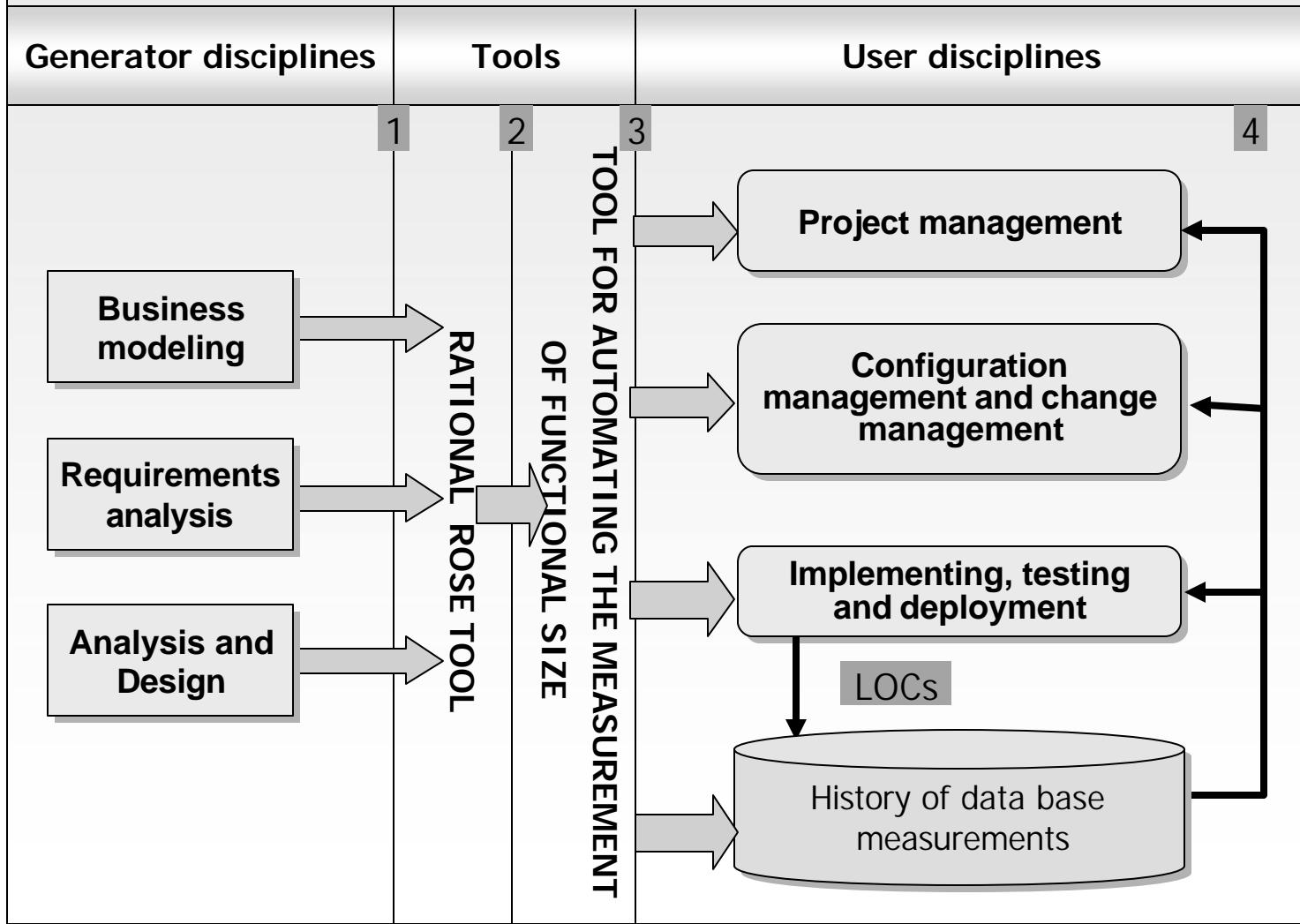


# RUP and measurement activity

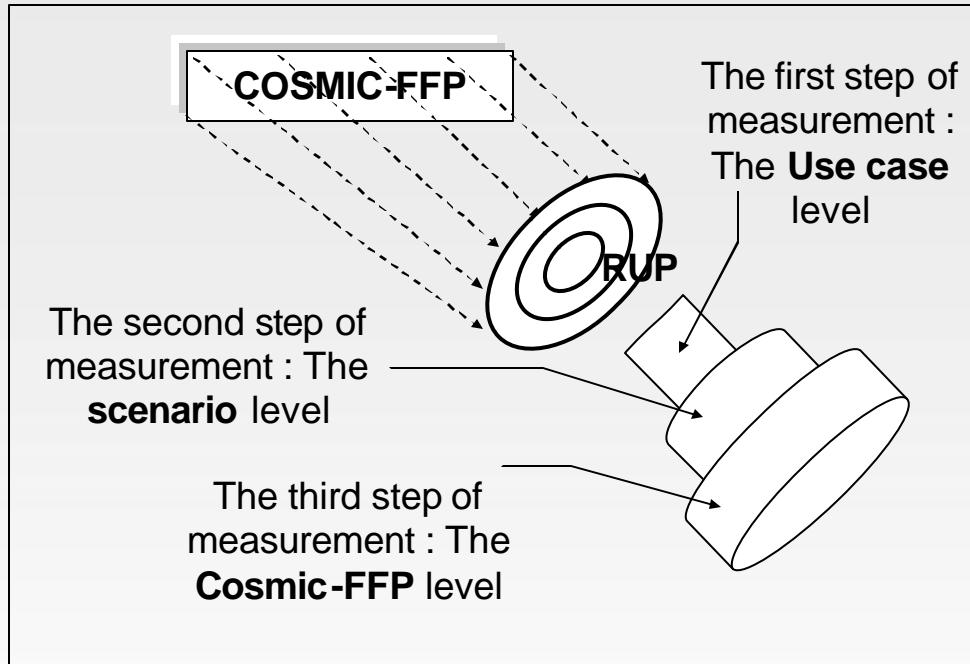


# RUP and measurement activity

## Measurement activity



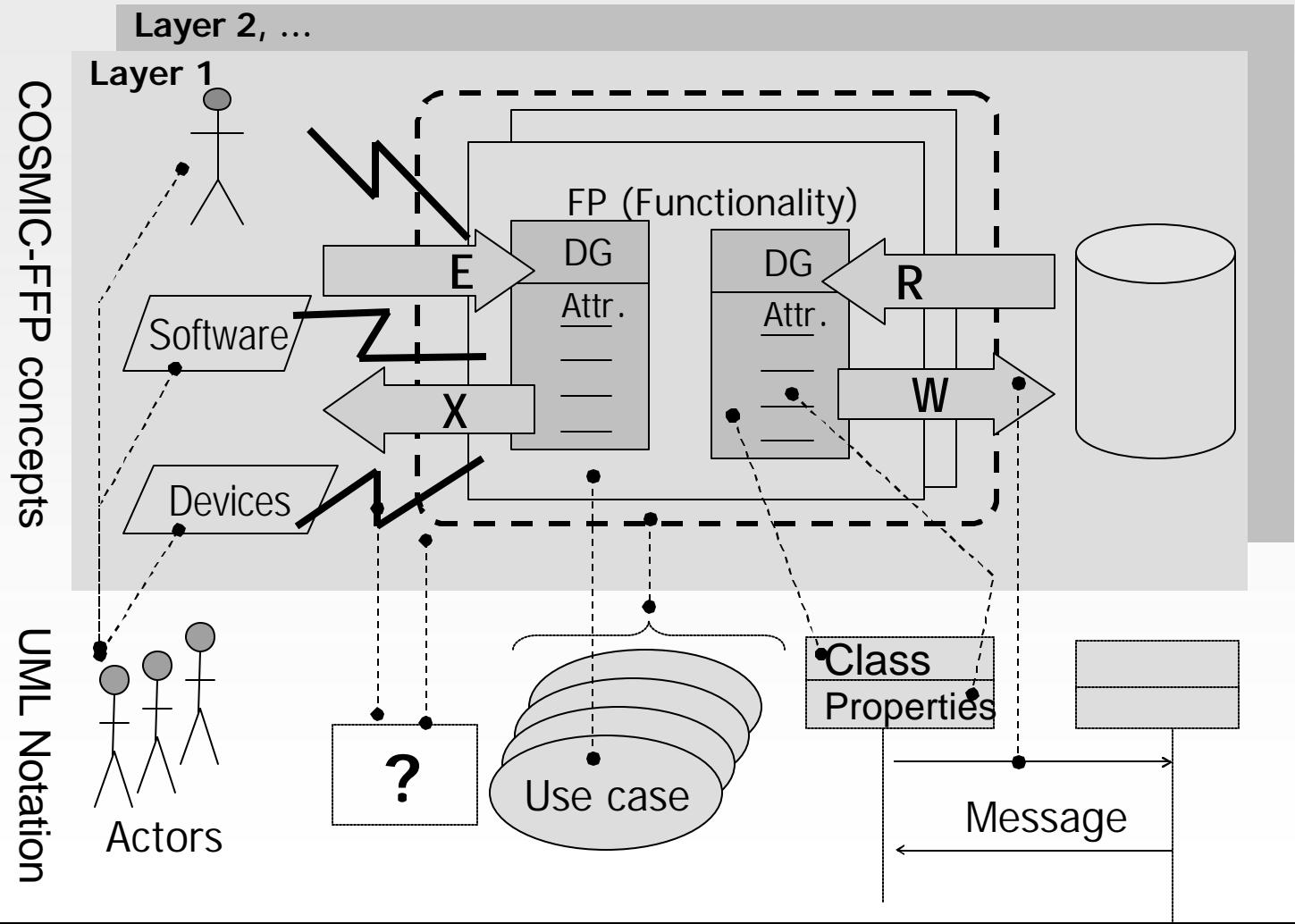
# Automated measurement



***Automation is very useful  
but needs oversight***

# Automated measurement

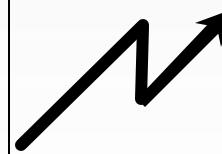
## Mapping of COSMIC-FFP concepts to UML



# Automated measurement

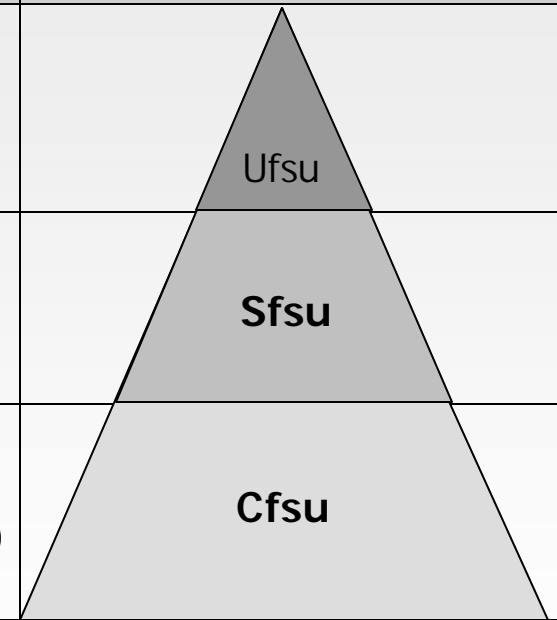
## Mapping of COSMIC-FFP concepts to UML

COSMIC-FFP Concept	UML equivalent
<b>Software boundary</b>	<b>Use case diagram</b> ✓
<b>Software Layer</b>	<b>No UML equivalent (Has to be identified manually)</b>
<b>COSMIC-FFP user</b>	<b>UML actor</b> ✓
<b>Functional process</b>	<b>Use case</b> ✓
<b>Data movement</b>	<b>Operation (message)</b> ✓
<b>Triggering event</b>	<b>No UML equivalent (A new UML stereotype is created to distinguish a trigger event from a simple message in use-case diagrams )</b>
<b>Data group</b>	<b>UML class</b> ✓
<b>Data attribute</b>	<b>Class property</b> ✓



# Automated measurement

## Measurement levels

Development phase	RUP artifacts used	Precursor Indicators (numbers)	Unit convention
<ul style="list-style-type: none"> <li>• Business modeling</li> <li>• Requirements analysis</li> </ul>	<ul style="list-style-type: none"> <li>• Use-case diagrams</li> </ul>	<ul style="list-style-type: none"> <li>• Use-cases</li> <li>• Actors</li> <li>• Interactions</li> </ul>	
<ul style="list-style-type: none"> <li>• Analyse &amp; Design</li> </ul>	<ul style="list-style-type: none"> <li>• Scenario diagrams</li> </ul>	<ul style="list-style-type: none"> <li>• Scenarios</li> <li>• Objets</li> </ul>	
<ul style="list-style-type: none"> <li>• Analyse &amp; Design</li> </ul>	<ul style="list-style-type: none"> <li>• Detailed scenarios</li> </ul>	<ul style="list-style-type: none"> <li>• Data movements</li> <li>• Type (E,X,R,W)</li> </ul>	

$x \text{ Ufsu} = y \text{ Sfsu} = z \text{ Cfsu}$

HIGH Abstraction level LOW



# Solution Overview

***Tool basis :***  
*Mapping of COSMIC-FFP  
concepts to UML notation*

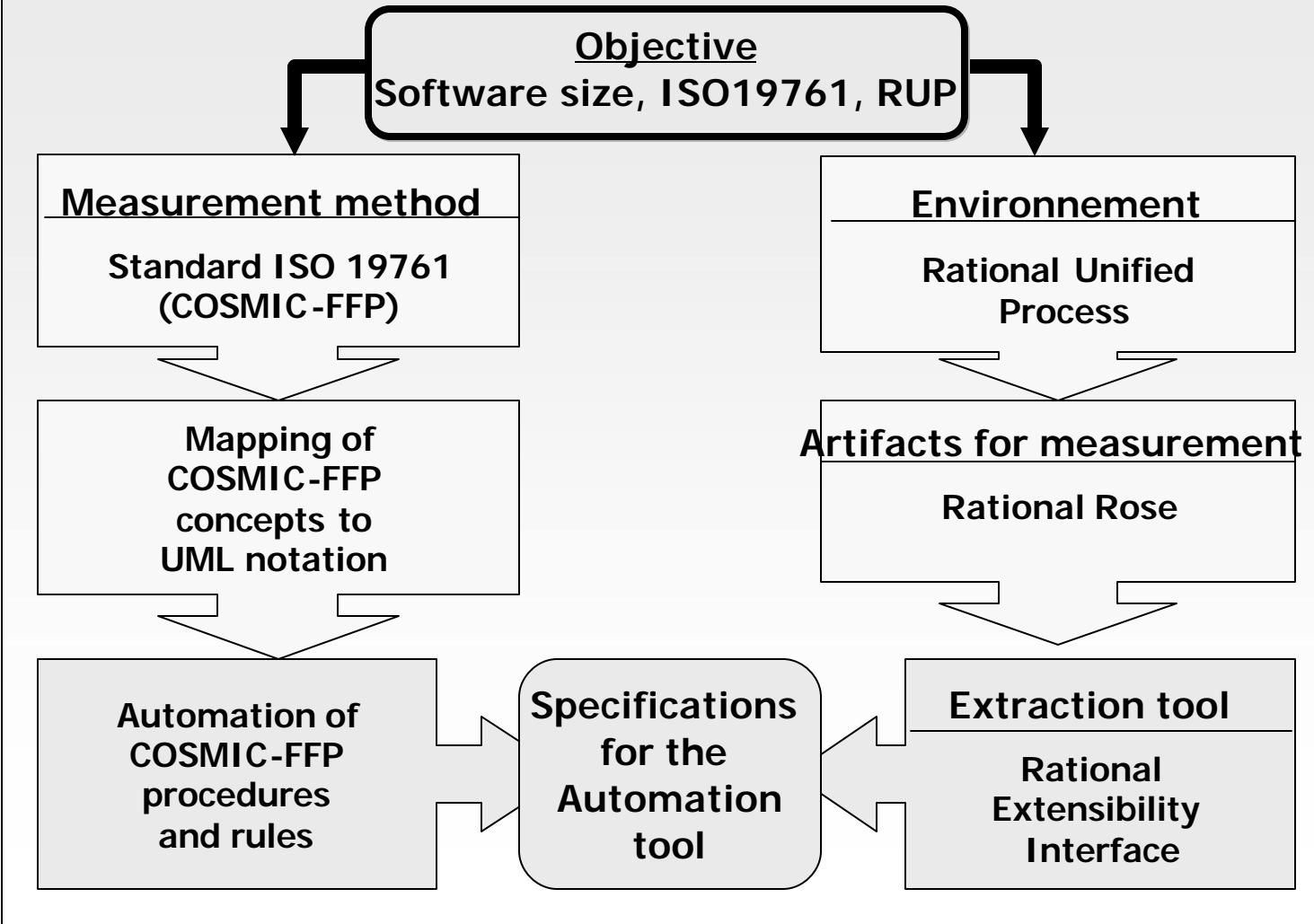


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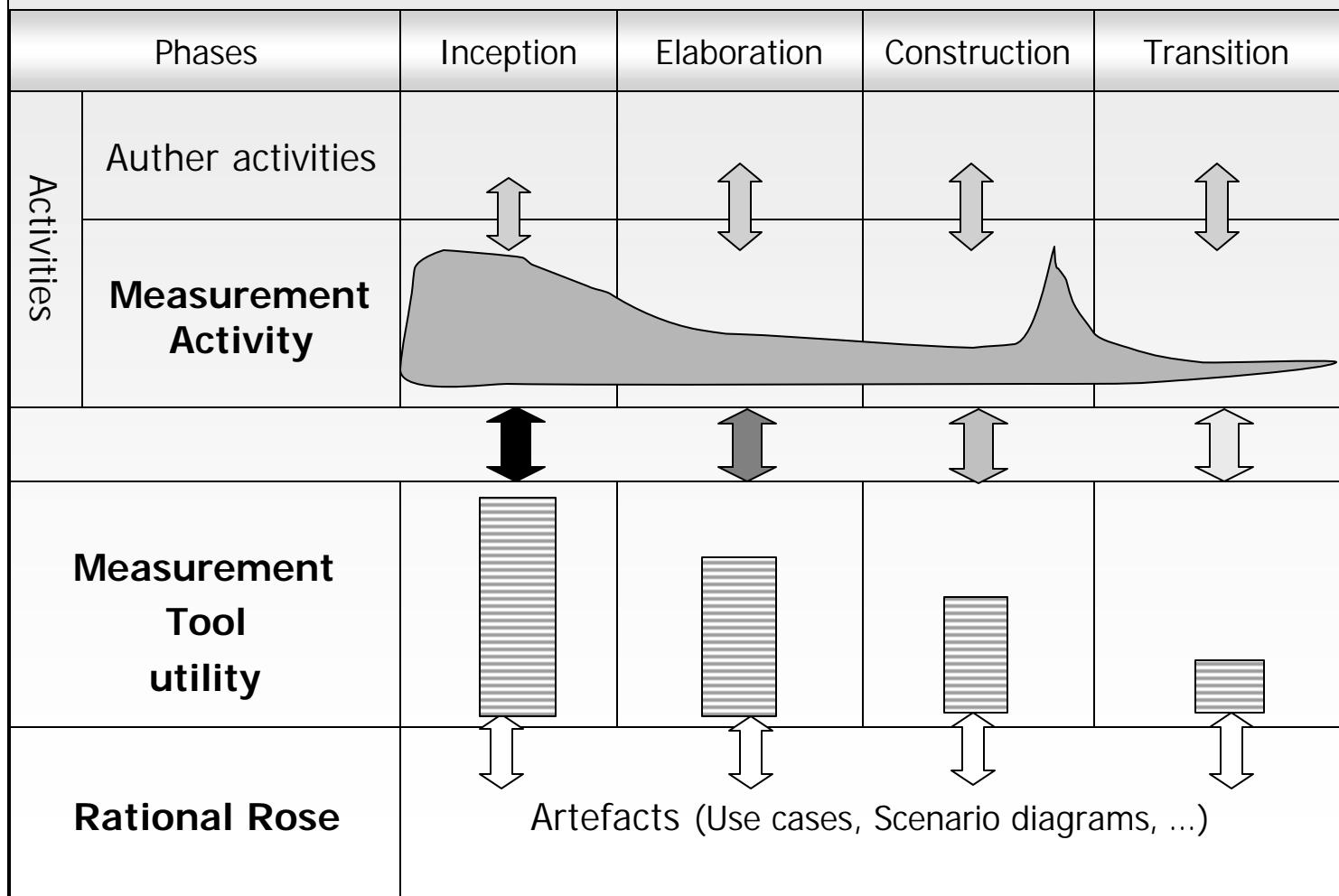
# Solution Overview

## Architecture of the solution



# Solution Overview

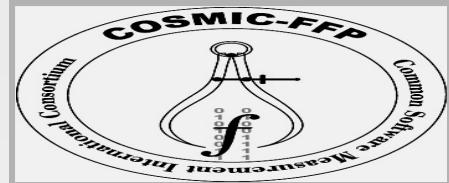
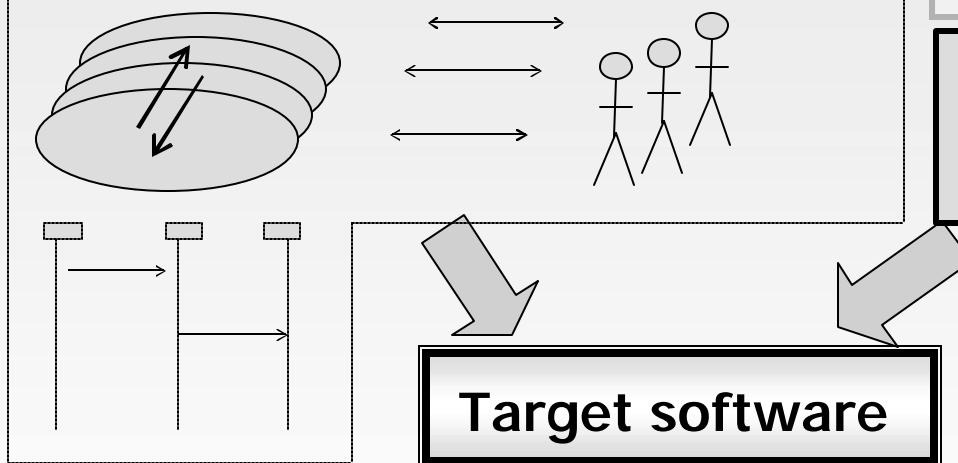
## Measurement activity



# Solution Overview

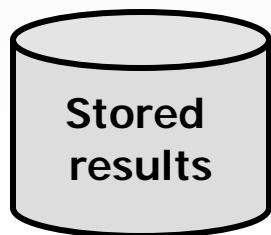
## Tool implementation

**Artifacts of the project to be measured  
(in Rational Rose environment)**



**COSMIC-FFP  
Rules and  
Procedures**

**Target software**

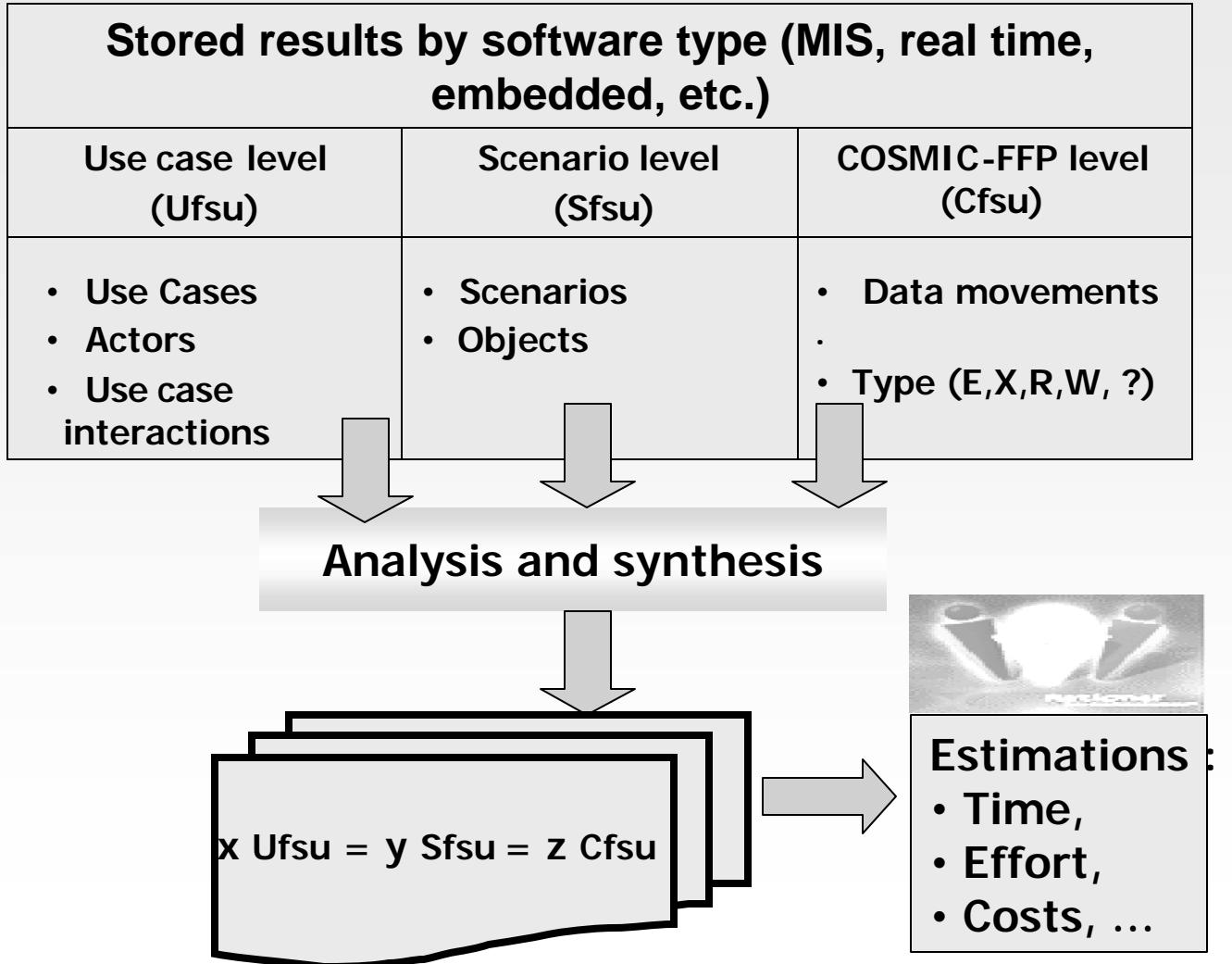


**Functional size**

**Editing /  
Printing  
results**

# Solution Overview

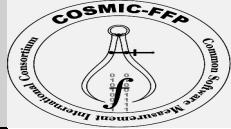
## The three measurement levels





# Results

*Integrating the  
measurement tool  
as an Add-In to  
Rational Rose*



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# Results

## Results - Main screen

Rational Rose - Rice Cooker.mdl

File Edit View Browse Debugger Tools Add-Ins Window Help

Functional Size Count for 'Rice Cooker' project : General results

Functional Processes	Scenarios	Functional Sub-Process	Data Group
Control Heater Select Cooking Mode Set Target Temperature Control Indicator Lamps	Control heater	(R) Receive actual temperature (?) Read target temperature (X) Set heater status	Actual temperature (Voir log erreur) Heater status

Selected Process : **Control Heater** Trigger event : **5 s clock signal** Scenarios number : **1** Size (Cfsu) : **3**

Résumé des tailles

Ufsu	Sfsu	Cfsu
Total Size ..... : <b>4 Ufsu(6,6)</b>	Total Size ..... : <b>4 Sfsu(15)</b>	Total Size (Cfsu). .... : <b>11</b>
Use Cases Number. .... : <b>4</b>	Scenarios Number. .... : <b>4</b>	Entries (E) number ..... : <b>3</b>
Actors Number. .... : <b>6</b>	Objets Total Number . : <b>15</b>	Exits (X) number ..... : <b>2</b>
Interactions Number. .... : <b>6</b>		Reads (R) number. .... : <b>3</b>
		Writes (W) number ..... : <b>1</b>
		Undetermined (E/X/R/W ?) .... : <b>2</b>

Language	Log Book Errors	Data Base	Results Type	Other
<input type="radio"/> Français	<a href="#">Consult Log</a>	<a href="#">Updade</a>	<a href="#">Detailed results</a>	<a href="#">Print results</a>
<input checked="" type="radio"/> English	<a href="#">Print Log</a>	<a href="#">Consult</a>	<a href="#">Summary by FP</a>	<a href="#">Close</a>
			<a href="#">Summary by DM</a>	

For Help, press F1

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NUM 20:28



# Results

## Results - By Functional process

Rational Rose - Rice Cooker.mdl

File Edit View Browse Debugger Tools Add-Ins Window Help

Use Case View Logical View Component View ABC

Calcul de la taille fonctionnelle pour le projet 'Rice Cooker' : Résultats détaillés

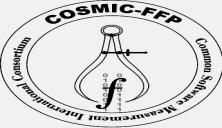
No	PID	Description du processus	Déclencheur	Description de Sous-processus	Groupe de données	S-P	Type	FFP	Total
1	1.1	Control Heater	5 s clock signal	Receive actual temperature Read target temperature Set heater status	Actual Temperature (Voir log erreurs) Heater Status	R	1		
						?	1		
						X	1		
									3
2	1.2	Select Cooking Mode	Mode switch pressed	Receive Cooking Mode Write Cooking Mode	Operator Cooking Mode	E	1		
						W	1		
									2
3	1.3	Set Target Temperature	30 s clock signal	Receive elapsed time Read cooking time Write target temperature	Elapsed Time Cooking Mode (Voir log erreurs)	E	1		
						R	1		
						?	1		
									3
Total d'unités COSMIC-FFP : 11									
<input type="button" value="OK"/>									
Line: 1546 Col: 14 Modified	<input type="button" value="Log"/>	<input type="button" value="X"/>							

For Help, press F1

Démarrer | Navigation en c... | Article.doc - Micr... | Projet COSMIC-F... | Rational Ros...

NUM

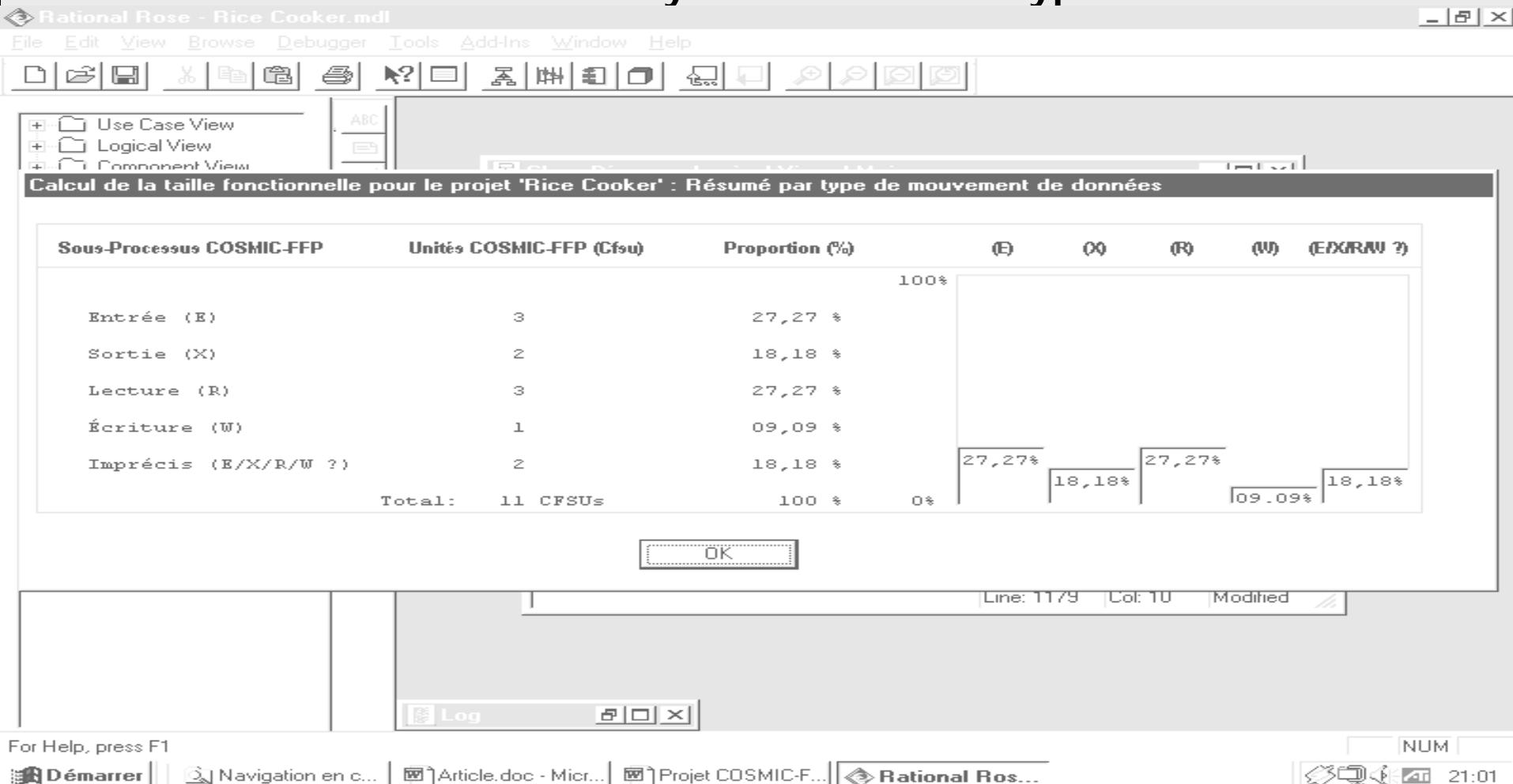
20:36



# Results



## Results - by Data Movement types





# Results



## Printed results

Calcul de la taille fonctionnelle pour le projet 'Rice Cooker' : Détail de la mesure - Classeur1								
Fichier Édition Affichage Insertion Format Outils Données Fenêtre ?								
A1 = No								
A	B	C	D	E	F	G	H	I
1	No	PID	Description du processus	Déclencheur	Description de Sous-proces	Groupe de donné	Type de sou	Unités COSMIC
2	1	1,1 Control Heater	5 s clock signal	Receive actual temperature	Actual Temperatu	Lecture (R)		1
3				Read target temperature	Target Temperatu	Lecture (R)		1
4				Set heater status	Heater Status	Sortie (X)		1
5							Total Partiel	3
6								
7	2	1,2 Select Cooking Mode	Mode switch pressed	Receive Cooking Mode	Operator	Entrée (E)		1
8				Write Cooking Mode	Cooking Mode	Écriture (W)		1
9							Total Partiel	2
10								
11	3	1,3 Set Target Temperature	30 s clock signal	Receive elapsed time	Elapsed Time	Entrée (E)		1
12				Read cooking time	Cooking Mode	Lecture (R)		1
13				Write target temperature	Target Temperatu	Écriture (W)		1
14							Total Partiel	3
15								
16	4	1,4 Control Indicator Lamps	30 s clock signal	Receive elapsed time	Elapsed Time	Entrée (E)		1
17				read cooking mode	Cooking Mode	Lecture (R)		1
18				Send Status to Lamps	Cooker Status	Sortie (X)		1
19							Total Partiel	3
20								
21								
22							Total général	11
23								
24								
25								
26								



# Results



## Measurement - Log

Rational Rose - Rice Cooker.mdl

File Edit View Browse Debugger Tools Add-Ins Window Help

Use Case View Logical View ABC

Functional Size Count for 'Rice Cooker' project : History Measurements Consultation

Projet Identification	Type	Ufsu			Sfsu		Cfsu			(EDGR/W?)	LOCs	
		Use Case	Actors	Interac.	Scénarios	Objects	Entries(E)	Exits(O)	Reads(R)			Writes(W)
Cosmic	2	5	2	9	4	0	7	7	0	0	4	0
Gestion	1	5	2	9	4	0	7	7	0	0	4	3
Gestions	4	5	2	9	4	0	7	7	0	0	4	0
Gestionogg	1	5	2	9	4	0	7	7	0	0	4	9
Gestion Glossairerel234	3	5	2	9	4	0	7	7	0	0	4	0
Rice Cooker	2	4	6	6	4	15	3	2	3	1	2	44
Valve Contrôle	4	1	5	1	1	9	4	1	13	3	0	6
lvcvf	1	0	0	0	0	0	0	0	0	0	0	0
2cvcv	2	0	0	0	0	0	0	0	0	0	0	0
3fvf	3	0	0	0	0	0	0	0	0	0	0	0
4vcvc	1	0	0	0	0	0	0	0	0	0	0	0
5vcv	1	0	0	0	0	0	0	0	0	0	0	0
6vcvcvc	1	0	0	0	0	0	0	0	0	0	0	0

Projets code type :  
1 - Management    2 - Real time  
3 - Embedded    4 - Other

OK

Line: 2 Col: 2

Log

For Help, press F1

Démarrer

Microsoft PowerPoint - [pre...]

Liens.doc - Microsoft Word

Rational Rose - Rice ...

Liens >>

19:26

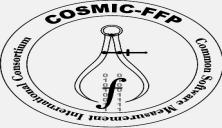
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# Conclusion



## Advantages:

- Measurement results at 3 levels of abstraction
- Good results with Rice Cooker & Valve Control case studies
  - ⇒ Delta = 1 cfsu between manual and automated measurements
- Requires rigor in the specifications

## Constraints:

- Operates on one layer
- Limited to Rational Rose tool



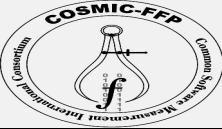


# References



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- P. Kruchten, "The RUP platform," Montréal-SPIN,Montréal,Canada, Nov. 2003, p 33
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# Questions



<http://www.internet.uqam.ca/web/t15040>

